

# Programming Design

## Algorithms and Recursion

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# Outline

- **Algorithms and complexity**
- Recursion
- Searching and sorting

# Introduction

- It is said that:
  - **Programming = Data structure + Algorithms.**
  - [http://en.wikipedia.org/wiki/Algorithms\\_%2B\\_Data\\_Structures\\_%3D\\_Programs](http://en.wikipedia.org/wiki/Algorithms_%2B_Data_Structures_%3D_Programs)
  - To design a program, choose data structures to store your data and choose algorithms to process your data.
- Each of “data structures” and “algorithms” requires one (or more) courses.
  - We will only give you very basic ideas.

# Algorithms

- Today we talk about **algorithms**, collections of steps for completing a task.
  - In general, an algorithm is used to **solve a problem**.
  - The most common strategy is to divide a problem into small pieces and then solve those **subproblems**.
  - We will introduce **recursion**, a way to solve a problem based on the solution/outcome of subproblems.
- For a problem, there may be multiple algorithms.
  - The first criterion, of course, is **correctness**.
  - **Time complexity** is typically the next for judging correct algorithms.
- As examples, we introduce two specific problems: **searching** and **sorting**.
- Let's watch a **video**!

# Example: listing all prime numbers

- Given an integer  $n$ , let's list all the **prime numbers** no greater than  $n$ .
- Consider the following (imprecise) algorithm:
  - For each number  $i$  no greater than  $n$ , check whether it is a prime number.
- To check whether  $i$  is a prime number:
  - Idea: If any number  $j < i$  can divide  $i$ ,  $i$  is not a prime number.
  - Algorithm: For each number  $j < i$ , check **whether  $j$  divides  $i$** . If there is any  $j$  that divides  $i$ , report no; otherwise, report yes.
- Before we write a program, we typically prefer to formalize our algorithm.
  - We write **pseudocodes**, a description of steps in words organized in a program structure.
  - This allows us to ignore the details of implementations.

# Example: listing all prime numbers

- One pseudocode for listing all prime numbers no greater than  $n$  is:

```
Given an integer  $n$ :  
for  $i$  from 2 to  $n$   
    assume that  $i$  is a prime number  
    for  $j$  from 2 to  $i - 1$   
        if  $j$  divides  $i$   
            set  $i$  to be a composite number  
    if  $i$  is still considered as prime  
        print  $i$ 
```

- Implementation:

```
for(int i = 2; i <= n; i++) {  
    bool isPrime = true;  
    for(int j = 2; j < i; j++) {  
        if(i % j == 0) {  
            isPrime = false;  
            break;  
        }  
    }  
    if(isPrime == true)  
        cout << i << " ";  
}
```

- Once we have described an algorithm in pseudocodes, implementation is easy.

# A full implementation

- Let's **modularize** our implementation:
  - **isPrime(int x)** determines whether the given integer x is a prime number.

```
bool isPrime(int x)
{
    for(int i = 2; i < x; i++)
    {
        if(x % i == 0)
            return false;
    }
    return true;
}
```

- Now we have a correct algorithm.
  - May we improve this algorithm?

```
#include <iostream>
using namespace std;

bool isPrime(int x);
int main()
{
    int n = 0;
    cin >> n;

    for(int i = 2; i <= n; i++)
    {
        if(isPrime(i) == true)
            cout << i << " ";
    }
    return 0;
}
```

# Improving our algorithm

- The algorithm can be **faster**:

```
bool isPrime(int x)
{
    for(int i = 2; i * i <= x; i++)
    {
        if(x % i == 0)
            return false;
    }
    return true;
}
```

- Do not use  $i \leq \sqrt{x}$  (why?).
- We improved the algorithm, **not** the implementation.
- May we do even better?

```
#include <iostream>
using namespace std;

bool isPrime(int x);
int main()
{
    int n = 0;
    cin >> n;

    for(int i = 2; i <= n; i++)
    {
        if(isPrime(i) == true)
            cout << i << " ";
    }
    return 0;
}
```



# Improving our algorithm further

- Let's consider a completely different algorithm:
  - Let's start from 2. Actually 2, 4, 6, 8, ... are all composite numbers.
  - For 3, actually 3, 6, 9, ... are all composite numbers.
  - We may use a **bottom-up approach** to **eliminate composite numbers**.
- The pseudocode (with comments):

```
Given a Boolean array  $A$  of length  $n$ 
Initialize all elements in  $A$  to be true // assuming prime
for  $i$  from 2 to  $n$ 
  if  $A_i$  is true
    print  $i$ 
    for  $j$  from 1 to  $\lfloor i/j \rfloor$  // eliminating composite numbers
      Set  $A[i \times j]$  to false
```

# Improving our algorithm further

```
#include <iostream>
using namespace std;

const int MAX_LEN = 10000;

void ruleOutPrime
    (int x, bool isPrime[], int n);

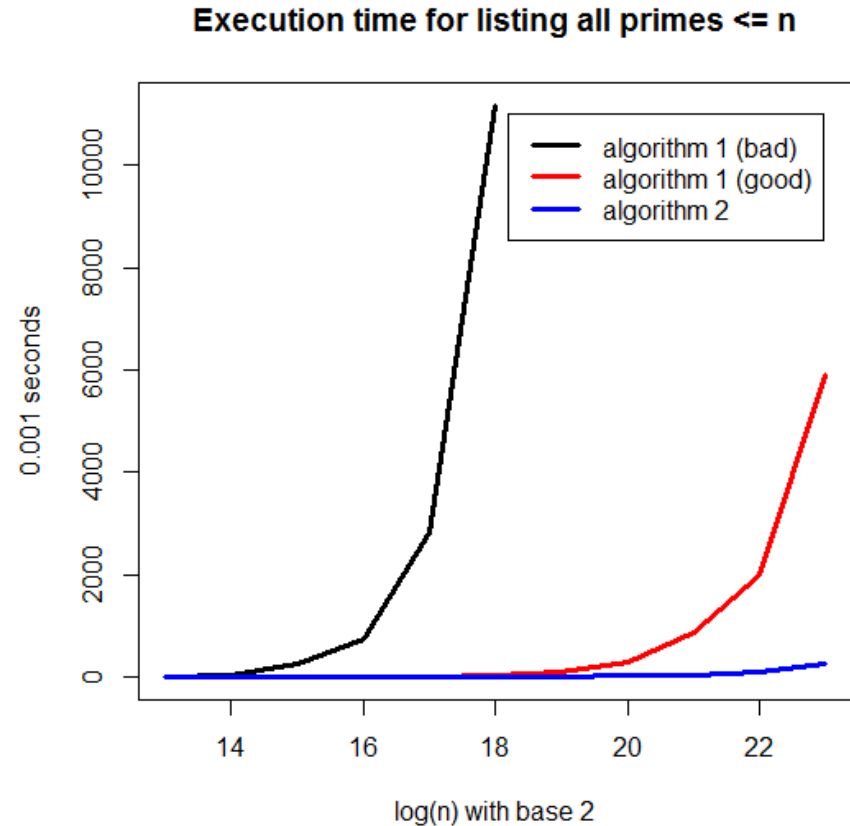
int main()
{
    int n = 0;
    cin >> n; // must < 10000
    bool isPrime[MAX_LEN] = {0};
    for(int i = 0; i < n; i++)
        isPrime[i] = true;
}
```

```
for(int i = 2; i <= n; i++)
{
    if(isPrime[i] == true)
    {
        cout << i << " ";
        ruleOutPrime(i, isPrime, n);
    }
}
return 0;

void ruleOutPrime
    (int x, bool isPrime[], int n)
{
    for(int i = 1; x * i < n; i++)
        isPrime[x * i] = false;
}
```

# Complexity

- When all the three algorithms are correct, they are not equally efficient.
- We typically care about the **complexity** of an algorithm:
  - **Time complexity**: the running time of an algorithm.
  - **Space complexity**: the amount of spaces used by an algorithm.
  - Time is typically more critical.
- Algorithm 2 is much faster!



# Complexity

- Running time may be affected by the hardware, number of programs running at the same time, etc.
  - The **number of basic operations** is a better measurement.
  - Basic operations include simple arithmetic, comparisons, etc.
- Convince yourself that algorithm 2 does fewer basic operations.
- The calculation of complexity needs training.
  - This will be formally introduced in Discrete Mathematics, Data Structures, and/or Algorithms.

# Outline

- Algorithms and complexity
- **Recursion**
- Searching and sorting

# Recursive functions

- A function is **recursive** if it invokes itself (directly or indirectly).
- The process of using recursive functions is called **recursion**.
- Why recursion?
  - Many problems can be solved by dividing the original problem into one or several smaller pieces of **subproblems**.
  - Typically subproblems are **quite similar** to the original problem.
  - With recursion, we write one function to solve the problem by **using the same function** to solve subproblems.

# Example 1: finding the maximum

- Suppose that we want to find the maximum number in an array  $A[1..n]$  (which means  $A$  is of size  $n$ ).
  - Is there any subproblem whose solution can be utilized?
  - Subproblem: Finding the maximum in an array with size smaller than  $n$ .
- A strategy:
  - Subtask 1: First find the maximum of  $A[1..(n - 1)]$ .
  - Subtask 2: Then compare that with  $A[n]$ .
- How would you visualize this strategy?
- While subtask 2 is simple, subtask 1 is **similar** to the original task.
  - It can be solved with the **same** strategy!

# Example 1: finding the maximum

- Let's try to implement the strategy.
- First, I know I need to write a function whose header is:

```
double max(double array[], int len);
```

- This function returns the maximum in **array** (containing **len** elements).
- I **want** this to happen, though at this moment I do not know how.
- Now let's implement it:
  - If the function **really works**, subtask 1 can be completed by invoking

```
double subMax = max(array, len - 1);
```

- Subtask 2 is done by comparing **subMax** and **array[len - 1]**.



# Example 1: finding the maximum

- A (wrong) implementation:
- What will happen if we really invoke this function?
  - The program will not terminate!
  - Even when **len** is 1 in an invocation, we will still try to invoke **max(array, 0)**.
- For an array whose size is 1:
  - That number is the maximum!
- With this, we can add a **stopping condition** into our function.

```
double max(double array[], int len)
{
    double subMax = max(array, len - 1);
    if(array[len - 1] > subMax)
        return array[len - 1];
    else
        return subMax;
}

int main()
{
    double a[5] = {5, 7, 2, 4, 3};
    cout << max(a, 5);
    return 0;
}
```

# Example 1: finding the maximum

- A correct implementation is:
- What is the outcome?

```
int main()
{
    double a[5] = {5, 7, 2, 4, 3};
    cout << max(a, 5);
    return 0;
}
```

- Both **else** can be removed. Why?

```
double max(double array[], int len)
{
    if(len == 1) // stopping condition
        return array[0];
    else
    {
        // recursive call
        double subMax = max (array, len - 1);
        if (array[len - 1] > subMax)
            return array[len - 1];
        else
            return subMax;
    }
}
```

# Example 1: finding the maximum

- Is it okay to remove both **else**? Why?

```
double max(double array[], int len)
{
    if(len == 1) // stopping condition
        return array[0];
    else
    {
        // recursive call
        double subMax = max (array, len - 1);
        if(array[len - 1] > subMax)
            return array[len - 1];
        else
            return subMax;
    }
}
```

```
double max(double array[], int len)
{
    if(len == 1) // stopping condition
        return array[0];
    // recursive call
    double subMax = max (array, len - 1);
    if(array[len - 1] > subMax)
        return array[len - 1];
    return subMax;
}
```

## Example 2: computing factorials

- How to write a function that computes the factorial of  $n$ ?
  - A subproblem: computing the factorial of  $n - 1$ .
  - A strategy: First calculate the factorial of  $n - 1$ , then multiply it with  $n$ .

```
int factorial(int n)
{
    if(n == 1) // stopping condition
        return 1;
    else
        // recursive call
        return factorial(n - 1) * n;
}
```

## Example 2: computing factorials

- When we invoke this function with argument 4:
- **factorial(4)**
  - = **factorial(3) \* 4**
  - = **(factorial(2) \* 3) \* 4**
  - = **((factorial(1) \* 2) \* 3) \* 4**
  - = **((1 \* 2) \* 3) \* 4**
  - = **(2 \* 3) \* 4**
  - = **6 \* 4**
  - = **24**

# Example 3: the Fibonacci sequence

- Write a recursive function to find the  $n$ th Fibonacci number.
  - The Fibonacci sequence is 1, 1, 2, 3, 5, 8, 13, 21, .... Each number is the sum of the two preceding numbers.
  - The  $n$ th value can be found once we know the  $(n - 1)$ th and  $(n - 2)$ th values.

```
int fib(int n)
{
    if(n == 1)
        return 1;
    else if(n == 2)
        return 1;
    else // two recursive calls
        return (fib(n - 1) + fib(n - 2));
}
```

# Some remarks

- There must be a **stopping condition** in a recursive function. Otherwise, the program will not terminate.
- In many cases, a recursive strategy can also be implemented with **loops**.
  - E.g., writing a loop for finding a maximum and factorial.
  - But sometimes it is hard to use loops to imitate a recursive function.
- Compared with an equivalent iterative function, a recursive implementation is usually **simpler** and **easier to understand**.
- However, it generally uses **more memory spaces** and is **more time-consuming**.
  - Invoking functions has some cost.

# Complexity issue of recursion

- In some cases, recursion is efficient enough.
  - E.g., finding a maximum or calculating the factorial.
- In some cases, however, recursion can be very **inefficient!**
  - E.g., Fibonacci.
- Let's compare the efficiency of two different implementations.



# Complexity issue of recursion

- Two implementations:

```
int fib(int n)
{
    if(n == 1)
        return 1;
    else if(n == 2)
        return 1;
    else // two recursive calls
        return (fib(n-1) + fib(n-2));
}
```

```
double fibRepetitive(int n)
{
    if(n == 1 || n == 2)
        return 1;
    int fib1 = 1, fib2 = 1;
    int fib3 = 0;
    for(int i = 2; i < n; i++)
    {
        fib3 = fib1 + fib2;
        fib1 = fib2;
        fib2 = fib3;
    }
    return fib3;
}
```

# Complexity issue of recursion

- Which one is faster?

```
int main()
{
    int n = 0;
    cin >> n;
    cout << fibRepetitive(n) << "\n"; // algorithm 1
    cout << fib(n) << "\n"; // algorithm 2
    return 0;
}
```

# Polynomial time vs. exponential time

- Given  $n$ :
  - The repetitive way has around  $c_1n$  steps, where  $c_1 > 0$  is a constant.
  - The recursive way has around  $c_22^n$  steps, where  $c_2 > 0$  is a constant.
- When  $n$  is large enough,  $c_22^n$  is much larger than  $c_1n$ .
  - Even if  $c_1 \ll c_2!$
  - We say the repetitive way is **more efficient**.
- Technically, we say that:
  - The repetitive way is a **polynomial-time** algorithm
  - The recursive way is an **exponential-time** algorithm.
- In general, an exponential-time algorithm is just too inefficient.

# Power of recursion

- Though recursion is sometimes inefficient, typically implementation is easier.
- Let's consider the classic example “**Hanoi Tower**”.
  - There are three pillars and disks of different sizes which can slide onto any pillar. Disc  $i$  is smaller than disc  $j$  if  $i < j$ .
  - A large disc cannot be placed on top of a small disc.
- Initially, all discs are at pillar A. We want to move them to pillar C:
  - Only one disk can be moved at a time.
  - Each move consists of taking the upper disk from one of the stacks and placing it on top of another stack.
- Let's watch a **video**!
- What are the steps that solve the Hanoi Tower problem in the fastest way?

# A recursive implementation

```
void hanoi(char from, char via,
           char to, int disc)
{
    if(disc == 1)
        cout << "From " << from
              << " to " << to << "\n";
    else
    {
        hanoi(from, to, via, disc - 1);
        cout << "From " << from
              << " to " << to << "\n";
        hanoi(via, from, to, disc - 1);
    }
}
```

```
#include <iostream>
using namespace std;

int main()
{
    int disc = 0; // number of discs
    cin >> disc;
    char a = 'A', b = 'B', c = 'C';

    hanoi(a, b, c, disc);

    return 0;
}
```

- Is there a good way of solving the Hanoi Tower problem iteratively?

# Outline

- Algorithms and complexity
- Recursion
- **Searching and sorting**

# Searching

- One fundamental task in computation is to **search** for an element.
  - We want to determine whether an element exists in a set.
  - If yes, we want to locate that element.
  - E.g., looking for a string in an article.
- Here we will discuss how to search for an integer in an one-dimensional array.
- Whether the array is **sorted** makes a big difference.

# Searching

- Consider an integer array  $A[1..n]$  and an integer  $p$ .
- How to determine whether  $p$  exists in  $A$ ?
- If so, where is it?
  - Assume that we only need to find one  $p$  even if there are multiple.
- Suppose that the array is unsorted.
- One of the most straightforward way is to apply a **linear search**.
  - Compare each element with  $p$  **one by one**, from the first to the last.
  - Whenever we find a match, report its location.
  - Conclude that  $p$  does not exist if we end up with nothing.
- The number of operations we need to execute is roughly proportional to  $n$ .



# Binary search

- What if the array is sorted?
- We may still apply the linear search.
- However, we may improve the efficiency by implementing a **binary search**.
  - First, we compare  $p$  with the median  $m$  (e.g.,  $A[(n + 1) / 2]$  if  $n$  is odd).
  - If  $p$  equals  $m$ , bingo!
  - If  $p < m$ , we know  $p$  must exist in **the first half** of  $A$  if it exists.
  - If  $p > m$ , we know  $p$  must exist in **the second half** of  $A$  if it exists.
  - For the latter two cases, we will continue searching in the **subarray**.
- Let's watch a **video**!

# Binary search: pseudocode

```
binarySearch(a sorted array  $A$ , search in between  $from$  and  $to$ , search for  $p$ )  
if  $n = 1$   
    return true if  $A_{from} = p$ ; return false otherwise  
else  
    let  $median$  be  $\text{floor}((from + to) / 2)$   
    if  $p = A_{median}$   
        return true  
    else if  $p < A_{median}$   
        return binarySearch( $A$ ,  $from$ ,  $median$ ,  $p$ )  
    else  
        return binarySearch( $A$ ,  $median + 1$ ,  $to$ ,  $p$ )
```

# Linear search vs. binary search

- In binary search, the number of instructions to be executed is roughly proportional to  $\log_2 n$ .
- So binary search is **much more efficient** than linear search!
  - The difference is huge if the array is large.
  - However, binary search is possible only if the array is sorted.
  - Is it worthwhile to sort an array before we search it?
- It is natural to implement binary search with **recursion**.
  - A subproblem is to search for the element in one half of the array.
- Binary search can also be implemented with repetition.
  - Is it natural to do so?

# Sorting

- Given a one-dimensional integer array  $A$  of size  $n$ , how to sort it?
- Given numbers 6, 9, 3, 4, and 7, how would you sort them?
- Recall what you typically do when you play poker:
  - First put the first number 6 aside.
  - Compare the second number 9 with 6. Because  $9 > 6$ , put 9 to the right of 6.
  - Compare the third number 3 with the **sorted list** (6, 9). Because  $3 < 6$ , put 3 to the left of 6.
  - Compare 4 with (3, 6, 9). Because  $3 < 4 < 6$ , **insert** 4 in between 3 and 6.
  - Compare 7 with (3, 4, 6, 9). Because  $6 < 7 < 9$ , insert 7 in between 6 and 9.
  - The result is (3, 4, 6, 7, 9).
- Let's watch a **video**!

# Insertion sort

- The above algorithm is called **insertion sort**.
  - The key is to maintain a sorted list.
  - Then for each number in the unsorted list, **insert** it into the proper location so that the sorted list **remains sorted**.
- How would you implement the insertion sort?
  - Recursion or repetition?
  - If recursion, what is your strategy?

# (Non-repetitive) insertion sort

- The pseudocode:

```
insertionSort(a non-repetitive array  $A$ , the array length  $n$ , an index  $cutoff < n$ )  
// at any time,  $A_{1..cutoff}$  is sorted and  $A_{(cutoff+1)..n}$  is unsorted  
if  $A_{cutoff+1} < A_{1..cutoff}$   
    let  $p$  be 1  
else  
    find  $p$  such that  $A_{p-1} < A_{cutoff+1} < A_p$   
    insert  $A_{cutoff+1}$  to  $A_p$  and shift  $A_{p..cutoff}$  to  $A_{(p+1)..(cutoff+1)}$   
if  $cutoff + 1 < n$   
    insertionSort( $A$ ,  $n$ ,  $cutoff + 1$ )
```

- What if  $A$  is repetitive?

# Insertion sort

- Roughly how many instructions do we need for insertion sort?
  - We need to do  $n$  insertions.
  - To insert the  $k$ th value, we search for a position and shift some elements.
    - A linear search: at most  $k$  comparisons.
    - Shifting: at most  $k$  shifts.
  - Roughly we need  $1 + 2 + \dots + n$  operations, which is proportional to  $n^2$ .
- Does binary search help?

# Mergesort (Merge sort)

- Insertion sort is **simple** and fast!
  - Not really “fast”, but faster than many similar sorting algorithm.
  - Because its idea and implementation is simple, it is faster than most algorithms when the array size is **small**.
- Interestingly, there is another sorting algorithm:
  - Its idea is somewhat similar to insertion sort.
  - But it is significantly faster for large arrays!
- This algorithm is called **mergesort**.



# Mergesort (Merge sort)

- Recall that in an insertion sort, we need to insert one number into a sorted list for many times.
- A key observation is that “inserting” **another sorted list** of size  $k$  into a sorted list can be faster than inserting  $k$  separate numbers one by one!
  - So such “inserting” is actually “**merging**”.
- Given an unsorted array, we will:
  - First split the array into two parts, the first half and second half.
  - Then sort each subarray.
  - Finally, merge these two subarrays.
- Mergesort is perfect for recursion!

# Mergesort (Merge sort): pseudocode

```
mergeSort(an array  $A$ , the array length  $n$ )  
  let  $median$  be  $\text{floor}((1 + n) / 2)$   
  mergeSort( $A_{1..median}$ ,  $median$ ) // now  $A_{1..median}$  is sorted  
  mergeSort( $A_{(median + 1)..n}$ ,  $n - median + 1$ ) // now  $A_{(median + 1)..n}$  is sorted  
  merge  $A_{1..median}$  and  $A_{(median + 1)..n}$  // how?
```

# Mergesort (Merge sort)

- Interestingly, insertion sort is a special way of running mergesort.
  - Not splitting the array into two halves.
  - Instead, splitting it into  $A[1..n - 1]$  and  $A[n]$ .
- Once we use the “smart split”, the **efficiency** is improved a lot!
  - Insertion sort: Roughly proportional to  $n^2$ .
  - Merge sort: Roughly proportional to  $n \log n$ .
- A simple observation can make a huge difference!