

# Operations Research

## Integer Programming

Ling-Chieh Kung

Department of Information Management  
National Taiwan University

## Scheduling workforce again



- ▶ We know that United Airline developed an LP to determine the number of staffs in each of their service locations.
- ▶ The same problem is faced by Taco Bell.
  - ▶ It has more than 6500 restaurants in the US.
  - ▶ It asks how many staffs to have at each restaurant in each shift.
- ▶ Taco Bell developed an Integer Program (i.e., an LP with integer variables) to solve its workforce scheduling problem.
  - ▶ The number of staffs is typically **small!** Rounding is very inaccurate.
- ▶ \$13 million are saved per year.
- ▶ Read the short story in Section 11.5 and the article on CEIBA.

# Integer programming

- ▶ We have worked with LP for four weeks.
- ▶ In some cases, variables must only take **integer values**.
  - ▶ Producing tables and chairs in a big factory: fractional variables.
  - ▶ Selecting some books to sell (knapsack): integer variables.
  - ▶ United Airline vs. Taco Bell.
  - ▶ We will see other reasons to use integer variables.
- ▶ The subject of formulating and solving models with integer variables is **Integer Programming (IP)**.
  - ▶ An IP is typically a linear IP (LIP).
  - ▶ If the objective function or any functional constraint is nonlinear, it is a nonlinear IP (NLIP).
  - ▶ We will focus on linear IP in this course.

# Integer programming

- ▶ First, we will introduce one general **algorithm** for solving IPs.
  - ▶ It “decomposes” an IP to multiple LPs, solve all the LPs, and compares those outcomes to reach a conclusion.
  - ▶ Each LP is solved separately (with the simplex method or other ways).
  - ▶ In general, solving a large-scale IP can takes a very long time.
- ▶ We then demonstrate how to use **binary variables** to enrich our formulations and model more complicated situations.
- ▶ Read Sections 11.1–11.7 in the textbook.

# Road map

- ▶ **Linear relaxation.**
- ▶ Branch and bound.
- ▶ Integer programming formulation.

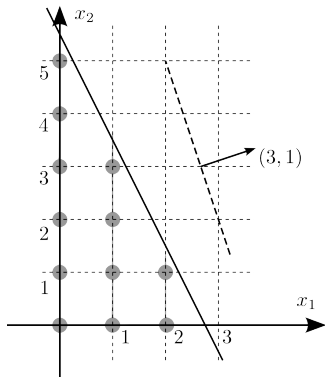
## Solving an IP

- ▶ Suppose we are given an IP, how may we solve it?
- ▶ The simplex method does not work!
  - ▶ The feasible region is not “a region”.
  - ▶ It is **discrete**.
  - ▶ There is no way to “move along edges”.
- ▶ But all we know is how to solve LPs. How about solving a **linear relaxation** first?

### Definition 1 (Linear relaxation)

*For a given IP, its linear relaxation is the resulting LP after removing all the integer constraints.*

$$\begin{aligned} \max \quad & 3x_1 + x_2 \\ \text{s.t.} \quad & 4x_1 + 2x_2 \leq 11 \\ & x_i \in \mathbb{Z}_+ \quad \forall i = 1, 2. \end{aligned}$$



## Linear relaxation

- ▶ What is the linear relaxation of

$$\begin{aligned} \max \quad & x_1 + x_2 \\ \text{s.t.} \quad & x_1 + 3x_2 \leq 10 \\ & 2x_1 - x_2 \geq 5 \\ & x_i \in \mathbb{Z}_+ \quad \forall i = 1, 2? \end{aligned}$$

- ▶  $\mathbb{Z}$  is the set of all integers.  $\mathbb{Z}_+$  is the set of all nonnegative integers.
- ▶ The linear relaxation is

$$\begin{aligned} \max \quad & x_1 + x_2 \\ \text{s.t.} \quad & x_1 + 3x_2 \leq 10 \\ & 2x_1 - x_2 \geq 5 \\ & x_i \geq 0 \quad \forall i = 1, 2. \end{aligned}$$

## Linear relaxation

- ▶ For the knapsack problem

$$\begin{aligned} \max \quad & 16x_1 + 22x_2 + 12x_3 + 8x_4 \\ \text{s.t.} \quad & 5x_1 + 7x_2 + 4x_3 + 3x_4 \leq 10 \\ & x_i \in \{0, 1\} \quad \forall i = 1, \dots, 4, \end{aligned}$$

the linear relaxation is

$$\begin{aligned} \max \quad & 16x_1 + 22x_2 + 12x_3 + 8x_4 \\ \text{s.t.} \quad & 5x_1 + 7x_2 + 4x_3 + 3x_4 \leq 10 \\ & x_i \in [0, 1] \quad \forall i = 1, \dots, 4, \end{aligned}$$

- ▶  $x_i \in [0, 1]$  is equivalent to  $x_i \geq 0$  and  $x_i \leq 1$ .



## Linear relaxation provides a bound

- ▶ For a **minimization** IP, its linear relaxation provides a **lower bound**.

### Proposition 1

*Let  $z^*$  and  $z'$  be the objective values associated to optimal solutions of a minimization IP and its linear relaxation, respectively, then  $z' \leq z^*$ .*

*Proof.* They have the same objective function. However, the linear relaxation's feasible region is (weakly) larger than that of the IP.  $\square$

- ▶ For a **maximization** IP, linear relaxation provides an **upper bound**.

## Linear relaxation may solve the IP

- ▶ If we are lucky, the linear relaxation may be infeasible or unbounded.
  - ▶ The IP is then infeasible or unbounded.
- ▶ If we are lucky, an optimal solution to the linear relaxation may be **feasible** to the original IP. When this happens, the IP is solved:

### Proposition 2

*Let  $x'$  be an optimal solutions to the linear relaxation of an IP. If  $x'$  is feasible to the IP, it is optimal to the IP.*

*Proof.* Suppose  $x'$  is not optimal to the IP, there must be another feasible solution  $x''$  that is better. However, as  $x''$  is feasible to the IP, it is also feasible to the linear relaxation, which implies that  $x'$  cannot be optimal to the linear relaxation. □

- ▶ What if we are **unlucky**?

## Rounding a fractional solution

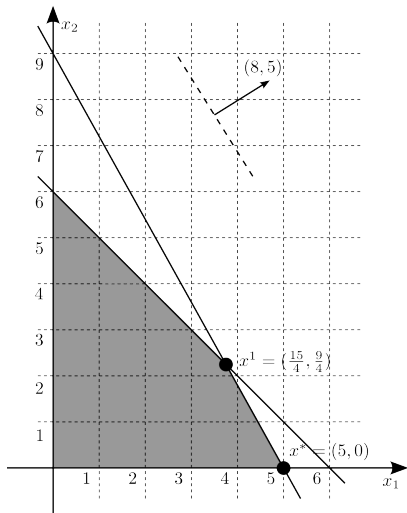
- ▶ Suppose we solve a linear relaxation with an LR-optimal solution  $x'$ .
  - ▶ “LR-optimal” means  $x'$  is optimal to the linear relaxation.
- ▶  $x'$ , however, has at least one variable violating the integer constraint in the original IP.
- ▶ We may choose to **round** the variable.
  - ▶ Round up or down?
  - ▶ Is the resulting solution always feasible?
  - ▶ Will the resulting solution be close to an IP-optimal solution  $x^*$ ?

## Rounding a fractional solution

- ▶ Consider the following IP

$$\begin{array}{ll} \max & 8x_1 + 5x_2 \\ \text{s.t.} & x_1 + x_2 \leq 6 \\ & 9x_1 + 5x_2 \leq 45 \\ & x_i \in \mathbb{Z}_+ \quad \forall i = 1, 2. \end{array}$$

- ▶  $x^* = (5, 0)$  is IP-optimal.
- ▶ But  $x^1 = (\frac{15}{4}, \frac{9}{4})$  is LR-optimal!
  - ▶ Rounding up any variable results in infeasible solutions.
  - ▶ None of the four grid points around  $x^1$  is optimal.
- ▶ We need a way that guarantees to find an optimal solution.

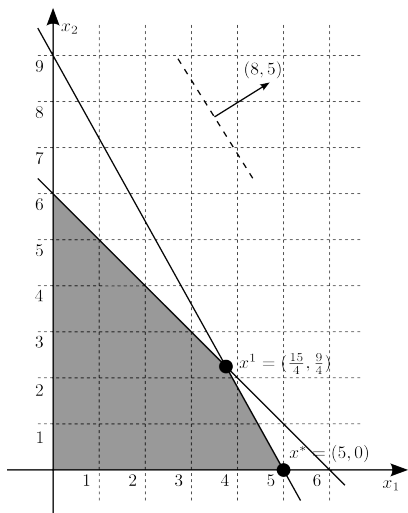


# Road map

- ▶ Linear relaxation.
- ▶ **Branch and bound.**
- ▶ Integer programming formulation.

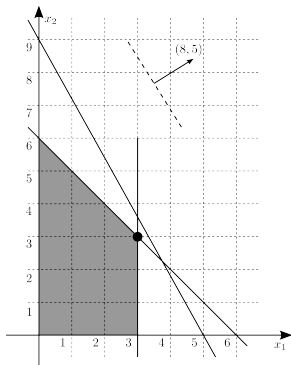
## Rounding a fractional solution

- ▶  $x^1 = (\frac{15}{4}, \frac{9}{4})$  is LR-optimal.
  - ▶ Rounding up or down  $x_1$  (i.e., adding  $x_1 = 4$  or  $x_1 = 3$  into the program) both **fail** to find the optimal solution.
  - ▶ Because we eliminate too many feasible points!
  - ▶ Instead of adding equalities, we should add **inequalities**.
- ▶ What will happen if we add  $x_1 \geq 4$  or  $x_1 \leq 3$  into the program?
- ▶ We will **branch** this problem into two problems, one with an additional constraint.

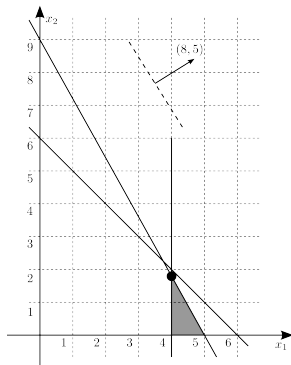


## Rounding a fractional solution

If we add  $x_1 \leq 3$ :



If we add  $x_1 \geq 4$ :



- ▶ The optimal solution to the IP must be contained in one of the above two feasible regions. Why?

## Rounding a fractional solution

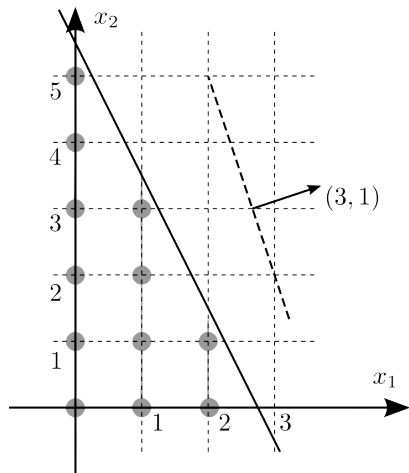
- ▶ So when we solve the linear relaxation and find any variable violating an integer constraint, we will **branch** this problem into two problems, one with an additional constraint.
- ▶ The two new programs are still linear programs.
- ▶ Once we solved them:
  - ▶ If their LR-optimal solutions are both IP-feasible, compare them and choose the better one.
  - ▶ If any of them results in a variable violating the integer constraint, **branch** on that variable **recursively**.
  - ▶ Eventually compare all the IP-feasible solutions we obtain.



# Example

- Let's illustrate the branch-and-bound algorithm with the following example:

$$(P_0) \quad \begin{array}{ll} \max & 3x_1 + x_2 \\ \text{s.t.} & 4x_1 + 2x_2 \leq 11 \\ & x_i \in \mathbb{Z}_+ \quad \forall i = 1, 2. \end{array}$$

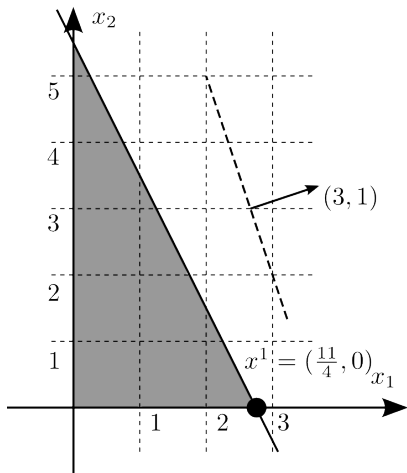


# Subproblem 1

- ▶ First we solve the linear relaxation:

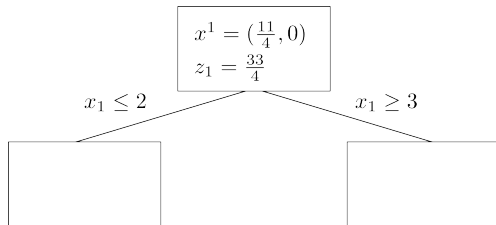
$$(P_1) \quad \begin{array}{ll} \max & 3x_1 + x_2 \\ \text{s.t.} & 4x_1 + 2x_2 \leq 11 \\ & x_i \geq 0 \quad \forall i = 1, 2. \end{array}$$

- ▶ The optimal solution is  $x^1 = (\frac{11}{4}, 0)$ .
- ▶ So we need to branch on  $x_1$ .



## Branching tree

- ▶ The branch and bound algorithm produces a **branching tree**.
  - ▶ Each node represents a subproblem (which is an LP).
  - ▶ Each time we branch on a variable, we create two child nodes.

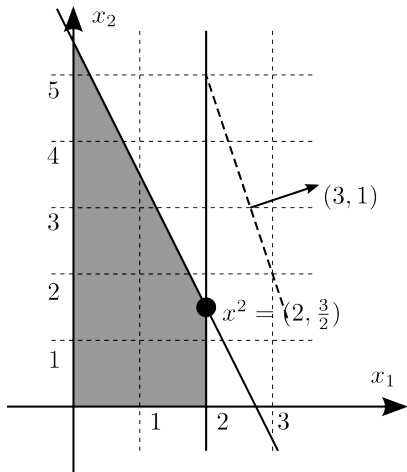


## Subproblem 2

- ▶ When we add  $x_1 \leq 2$ :

$$(P_2) \quad \begin{array}{llll} \max & 3x_1 & + & x_2 \\ \text{s.t.} & 4x_1 & + & 2x_2 \leq 11 \\ & x_1 & & \leq 2 \\ & x_i & \geq & 0 \quad \forall i = 1, 2. \end{array}$$

- ▶ An  $(P_2)$ -optimal solution is  $x^2 = (2, \frac{3}{2})$ .
  - ▶ So later we need to branch on  $x_2$ .
- ▶ Before that, let's solve  $(P_3)$ .

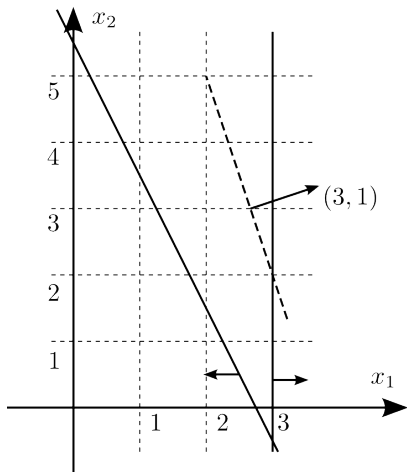


## Subproblem 3

- ▶ When we add  $x_1 \geq 3$ :

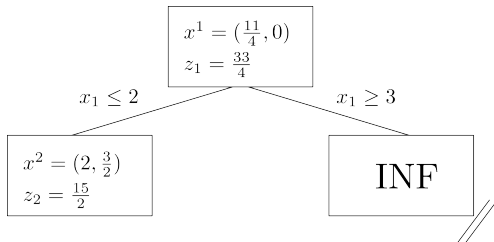
$$(P_3) \quad \begin{array}{llll} \max & 3x_1 & + & x_2 \\ \text{s.t.} & 4x_1 & + & 2x_2 \leq 11 \\ & x_1 & & \geq 3 \\ & x_i & \geq 0 & \forall i = 1, 2. \end{array}$$

- ▶ The problem is infeasible!
- ▶ This node is “dead” and does not produce any candidate solution.



## Branching tree

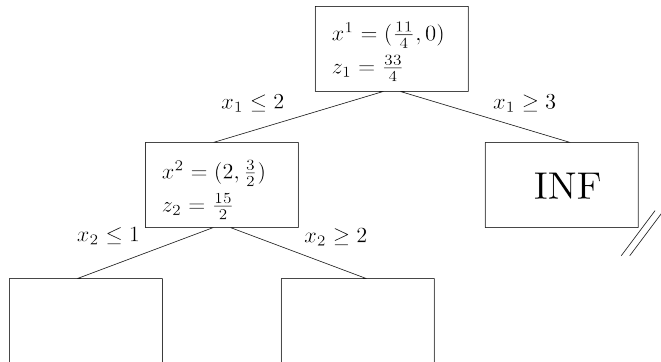
- ▶ The current progress can be summarized in the branching tree.



- ▶ Note that  $z_2 = 7.5 < 8.25 = z_1$ .
- ▶ In general, when we branch to the next level, the objective value associated with a subproblem-optimal solution will **always** be weakly **lower** (for a maximization problem). Why?

## Branching tree

- As  $x_2 = \frac{3}{2}$  in  $x^2$ , we will branch subproblem 2 on  $x_2$ .

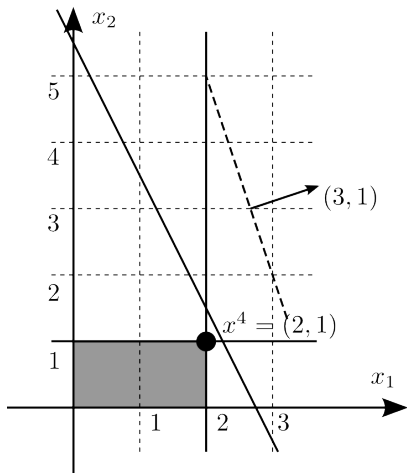


## Subproblem 4

- ▶ When we add  $x_2 \leq 1$ :

$$\begin{array}{rcll}
 \max & 3x_1 & + & x_2 \\
 \text{s.t.} & 4x_1 & + & 2x_2 \leq 11 \\
 (P_4) & x_1 & & \leq 2 \\
 & & & x_2 \leq 1 \\
 & x_i & \geq 0 & \forall i = 1, 2.
 \end{array}$$

- ▶ Note that we add  $x_2 \leq 1$  into subproblem 2, so  $x_1 \leq 2$  is still there.

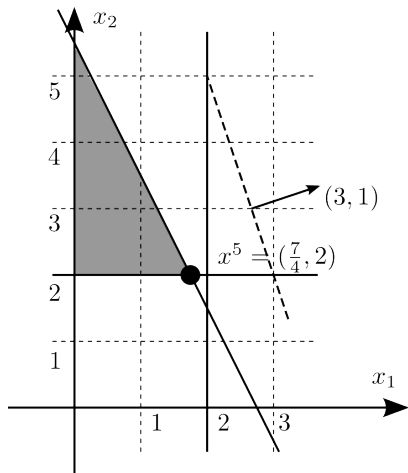




## Subproblem 5

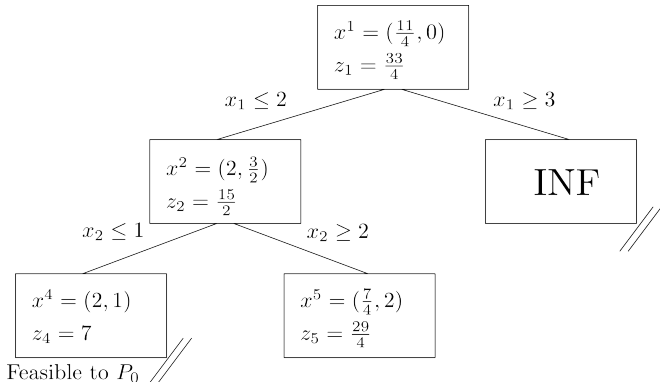
► When we add  $x_2 \geq 2$ :

$$(P_5) \quad \begin{array}{rcll} \max & 3x_1 & + & x_2 \\ \text{s.t.} & 4x_1 & + & 2x_2 \leq 11 \\ & x_1 & & \leq 2 \\ & & & x_2 \geq 2 \\ & x_i & \geq & 0 \quad \forall i = 1, 2. \end{array}$$



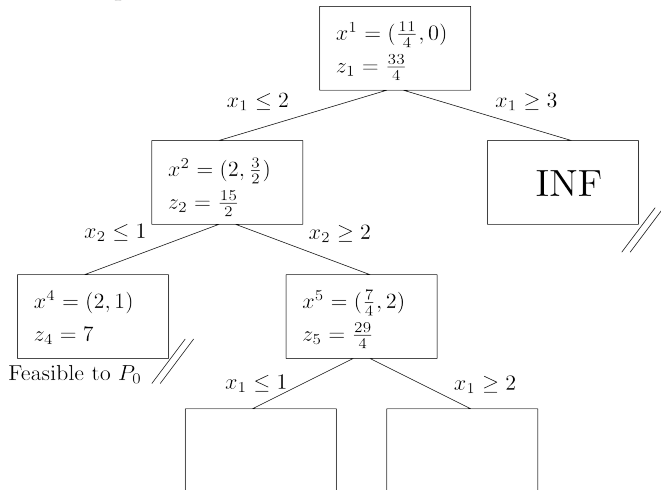
## Branching tree

- ▶  $x^4$  satisfies all the integer constraints.
- ▶ It is IP-feasible and thus a **candidate solution** to the original IP.
- ▶ But branching subproblem 5 may result in a better solution.



## Branching tree

- ▶ Let's branch subproblem 5 on  $x_1$ .

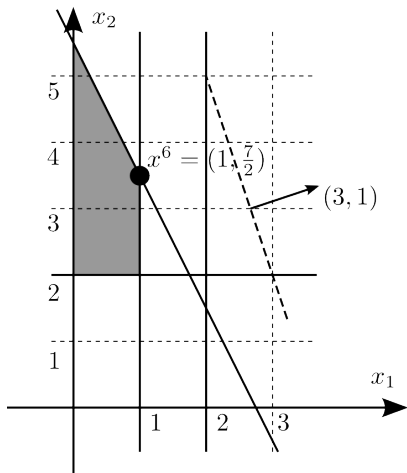


## Subproblem 6

- When we add  $x_1 \leq 1$ :

$$\begin{array}{rcll}
 \max & 3x_1 & + & x_2 \\
 \text{s.t.} & 4x_1 & + & 2x_2 \leq 11 \\
 (P_6) & x_1 & & \leq 2 \\
 & & & x_2 \geq 2 \\
 & x_1 & & \leq 1 \\
 & x_i & \geq 0 & \forall i = 1, 2.
 \end{array}$$

- $x^6 = (1, \frac{7}{2})$ . We may need to branch on  $x_2$  again. However, let's solve subproblem 7 first.

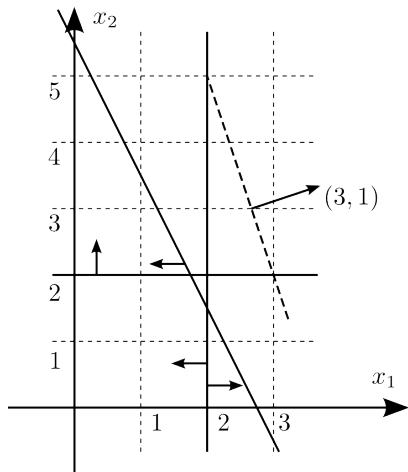


# Subproblem 7

- ▶ When we add  $x_1 \geq 2$ :

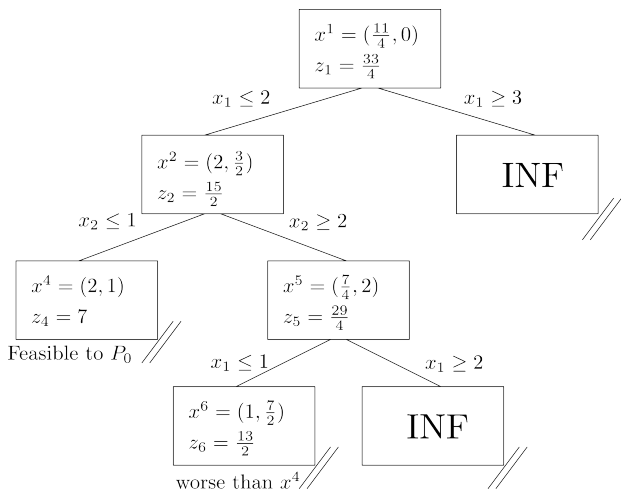
$$\begin{array}{rcll}
 \max & 3x_1 & + & x_2 & & \\
 \text{s.t.} & 4x_1 & + & 2x_2 & \leq & 11 \\
 (P_7) & & & x_1 & \leq & 2 \\
 & & & & & x_2 \geq 2 \\
 & & & x_1 & \geq & 2 \\
 & & & x_i & \geq 0 & \forall i = 1, 2.
 \end{array}$$

- ▶ The problem is infeasible.
- ▶ The node is “dead”.



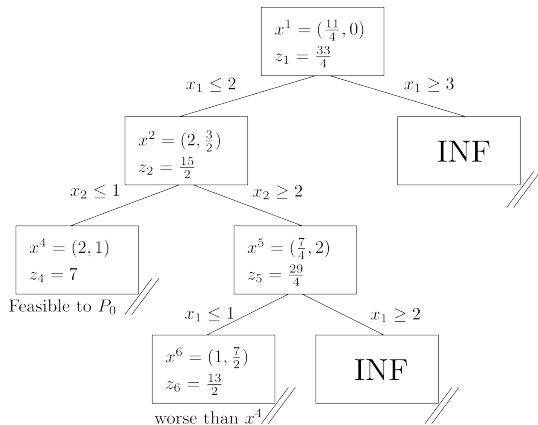
# Branching tree

- ▶ The only “alive” node is subproblem 6, with  $x_2$  fractional.
- ▶ Before we branch subproblem 6, consider the following:



# Bounding

- ▶  $z_6 = \frac{13}{2}$ . If we branch ( $P_6$ ), all the candidate solutions (if any) under it will be (weakly) **worse** than  $\frac{13}{2}$ .
- ▶ However,  $\frac{13}{2} < 7 = z_4$ , and  $x_4$  is already a candidate!
- ▶ So there is no need to branch ( $P_6$ ). This is the “**bounding**” situation in the branch-and-bound algorithm.
  - ▶ This allows us to solve fewer subproblems.



## Summary

- ▶ In running the branch-and-bound algorithm, we maintain a tree.
- ▶ If a subproblem-optimal solution is IP-feasible, set it to the candidate solution if it is currently the best among all IP-feasible solutions. Stop branching this node.
- ▶ If a subproblem is infeasible, stop branching this node.
- ▶ If a subproblem-optimal solution is not IP-feasible:
  - ▶ If it is better than the current candidate solution, branch.
  - ▶ Otherwise, stop branching.



## Another example

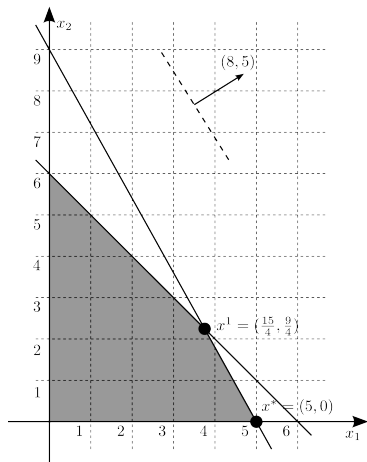
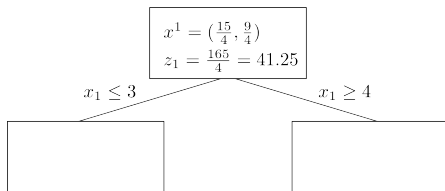
- ▶ Now let's go back to our motivating example:

$$(Q_0) \quad \begin{array}{ll} \max & 8x_1 + 5x_2 \\ \text{s.t.} & x_1 + x_2 \leq 6 \\ & 9x_1 + 5x_2 \leq 45 \\ & x_i \in \mathbb{Z}_+ \quad \forall i = 1, 2. \end{array}$$

- ▶ Let's solve it with the branch-and-bound algorithm.

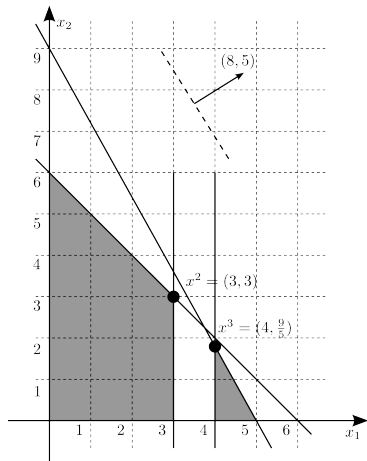
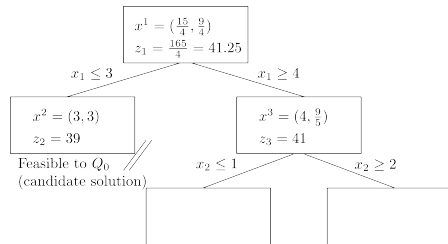
# Subproblem 1

- ▶  $x^1 = (\frac{15}{4}, \frac{9}{4})$ .
- ▶ We may branch on either variable. Let's branch on  $x_1$ .



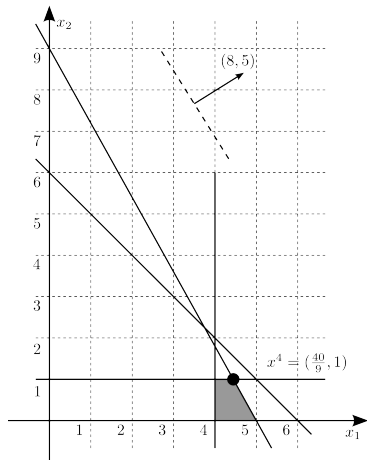
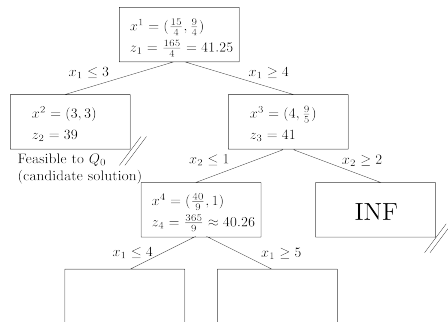
## Subproblems 2 and 3

- ▶ Subproblem 2 generates a candidate solution.
- ▶  $x^3 = (4, \frac{9}{5})$ . As  $z_3 = 41 > z_2 = 39$ , we should branch subproblem 3.



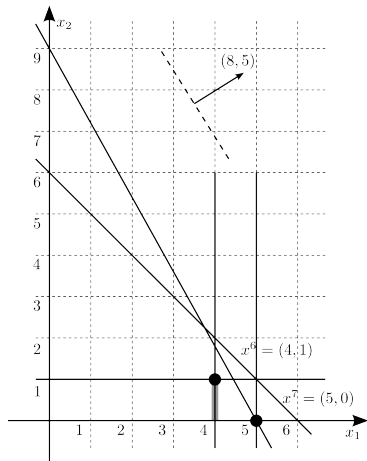
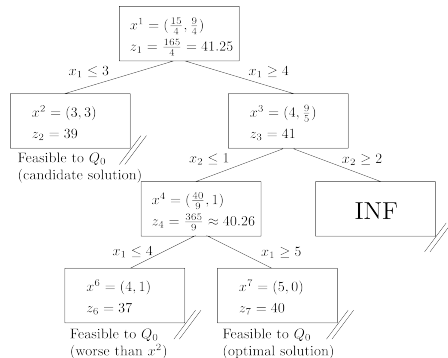
## Subproblems 4 and 5

- ▶  $x^4 = (\frac{40}{9}, 1)$ . As  $z_4 = 40.25 > z_2 = 39$ , we should branch subproblem 4.
- ▶ Subproblem 5 is infeasible.



# Subproblems 6 and 7

- ▶  $x^6 = (4, 1)$  but  $z_6 = 37 < 39 = z_2$ .
- ▶  $x^7 = (5, 0)$  and  $z_7 = 40 > 39 = z_2$ . As it is also the last node,  $x^7$  is an optimal solution.



## Remarks

- ▶ To select a node to branch:
  - ▶ Among all alive nodes, there are many different ways of selecting a node to branch.
  - ▶ One common approach is to branch the node with the highest objective value (for a maximization problem). Why?
  - ▶ Another popular approach is “once a node is branched, all its descendants are branched before any nondescendant. Why?”
- ▶ Choosing a variable to branch on is also a challenging task.
- ▶ The branch-and-bound algorithm guarantees to find an optimal solution, if one exists.
- ▶ However, it is an **exponential-time** algorithm.
  - ▶ Roughly speaking, with  $n$  integer variables, the number of subproblems solved is approximately proportional to  $2^n$ .

# Road map

- ▶ Linear relaxation.
- ▶ Branch and bound.
- ▶ **Integer programming formulation.**

## The knapsack problem

- ▶ We start our illustration with the classic **knapsack** problem.
- ▶ There are four items to select:

Item	1	2	3	4
Value (\$)	16	22	12	8
Weight(kg)	5	7	4	3

- ▶ The knapsack capacity is 10 kg.
- ▶ We maximize the total value without exceeding the knapsack capacity.
- ▶ The complete formulation:

$$\begin{aligned} \max \quad & 16x_1 + 22x_2 + 12x_3 + 8x_4 \\ \text{s.t.} \quad & 5x_1 + 7x_2 + 4x_3 + 3x_4 \leq 10 \\ & x_i \in \{0, 1\} \quad \forall i = 1, \dots, 4. \end{aligned}$$



## Requirements on selecting variables

- ▶ Integer programming allows us to implement some selection rules.
- ▶ At least/most some items:
  - ▶ Suppose we must select **at least** one item among items 2, 3, and 4:

$$x_2 + x_3 + x_4 \geq 1.$$

- ▶ Suppose we must select **at most** two items among items 1, 3, and 4:

$$x_1 + x_3 + x_4 \leq 2$$

## Requirements on selecting variables

▶ Or:

- ▶ Select item 2 or item 3:

$$x_2 + x_3 \geq 1.$$

- ▶ Select item 2; otherwise, items 3 and 4 together:

$$2x_2 + x_3 + x_4 \geq 2.$$

▶ If-else:

- ▶ If item 2 is selected, select item 3:

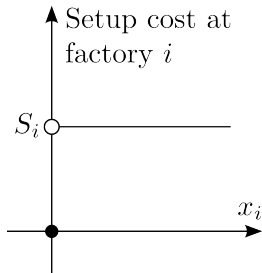
$$x_2 \leq x_3.$$

- ▶ If item 1 is selected, do not select items 3 and 4:

$$2(1 - x_1) \geq x_3 + x_4.$$

## Fixed-charge constraints

- ▶ Consider the following example:
- ▶  $n$  factories, 1 market, 1 product.
  - ▶ Capacity of factory  $i$ :  $K_i$ .
  - ▶ Unit production cost at factory  $i$ :  $C_i$ .
  - ▶ Demand:  $D$ .
  - ▶ We want to satisfy the demand with the minimum cost.
- ▶ **Setup cost** at factory  $i$ :  $S_i$ .
  - ▶ One needs to pay the setup cost as long as any **positive** amount of products is produced.



## Basic formulation

- ▶ Let the decision variables be

$x_i =$  production quantity at factory  $i$ ,  $i = 1, \dots, n$ ,

$$y_i = \begin{cases} 1 & \text{if some products are produced at factory } i, i = 1, \dots, n. \\ 0 & \text{o/w.} \end{cases}$$

- ▶ Objective function:

$$\min \sum_{i=1}^n C_i x_i + \sum_{i=1}^n S_i y_i.$$

- ▶ Capacity limitation:

$$x_i \leq K_i \quad \forall i = 1, \dots, n.$$

- ▶ Demand fulfillment:

$$\sum_{i=1}^n x_i \geq D.$$

## Setup costs

- ▶ How may we know whether we need to pay the setup cost at factory  $i$ ?
  - ▶ If  $x_i > 0$ ,  $y_i$  must be 1; if  $x_i = 0$ ,  $y_i$  should be 0.
- ▶ So the relationship between  $x_i$  and  $y_i$  should be:

$$x_i \leq K_i y_i \quad \forall i = 1, \dots, n.$$

- ▶ If  $x_i > 0$ ,  $y_i$  cannot be 0.
  - ▶ If  $x_i = 0$ ,  $y_i$  can be 0 or 1. Why  $y_i$  will always be 0 when  $x_i = 0$ ?
- ▶ Finally, binary and nonnegative constraints:

$$x_i \geq 0, y_i \in \{0, 1\} \quad \forall i = 1, \dots, n.$$

## Fixed-charge constraints

- ▶ The constraint  $x_i \leq K_i y_i$  is known as a **fixed-charge constraint**.
- ▶ In general, a fixed-charge constraint is

$$x \leq My.$$

- ▶ Both  $x$  and  $y$  are decision variables.
- ▶  $y \in \{0, 1\}$  is determined by  $x$ .
- ▶  $M$  must be set to be an **upper bound** of  $x$ .
- ▶ When  $x$  is binary,  $x \leq y$  is sufficient.
- ▶ We need to make  $M$  an upper bound of  $x$ .
  - ▶ For example,  $K_i$  is an upper bound of  $x_i$  in the factory example. Why?
  - ▶ What if there is no capacity limitation?

## At least/most some constraints

- ▶ Using a similar technique, we may **flexibly** select constraints.
- ▶ Suppose satisfying one of the two constraints

$$g_1(x) \leq b_1 \quad \text{and} \quad g_2(x) \leq b_2$$

is enough. How to formulate this situation?

- ▶ Let's define a binary variable

$$z = \begin{cases} 0 & \text{if } g_1(x) \leq b_1 \text{ is satisfied,} \\ 1 & \text{if } g_2(x) \leq b_2 \text{ is satisfied.} \end{cases}$$

- ▶ With  $M_i$  being an upper bound of each LHS, the following two constraints implement what we need:

$$\begin{aligned} g_1(x) - b_1 &\leq M_1 z \\ g_2(x) - b_2 &\leq M_2(1 - z). \end{aligned}$$

## At least/most some constraints

- ▶ Suppose at least two of the three constraints

$$g_i(x) \leq b_i, \quad i = 1, 2, 3,$$

must be satisfied. How to play the same trick?

- ▶ Let

$$z_i = \begin{cases} 1 & \text{if } g_i(x) \leq b_i \text{ is satisfied,} \\ 0 & \text{if } g_i(x) \leq b_i \text{ may be unsatisfied.} \end{cases}$$

- ▶ With  $M_i$  being an upper bound of each LHS, the following constraints are what we need:

$$g_i(x) - b_i \leq M_i(1 - z_i) \quad \forall i = 1, \dots, 3.$$

$$z_1 + z_2 + z_3 \geq 2.$$



## If-else constraints

- ▶ In some cases, if  $g_1(x) > b_1$  is satisfied, then  $g_2(x) \leq b_2$  must also be satisfied.
- ▶ How to model this situation?
  - ▶ First, note that “if  $A$  then  $B$ ”  $\Leftrightarrow$  “(not  $A$ ) or  $B$ ”.
  - ▶ So what we really want to do is  $g_1(x) \leq b_1$  or  $g_2(x) \leq b_2$ .
  - ▶ So simply select at least one of  $g_1(x) \leq b_1$  and  $g_2(x) \leq b_2$ !

## Route selection



- ▶ Waste Management Inc. operates an recycling network with 293 landfill sites, 16 waste-to-energy plants, 72 gas-to-energy facilities, 146 recycling plants, 346 transfer stations, and 435 collection depots.
  - ▶ 20000 routes must be go through by its vehicles in each day.
- ▶ How to determine a route?
  - ▶ Construct a network with nodes and edges.
  - ▶ Give each edge a **binary** variable: 1 if included and 0 otherwise.
  - ▶ Constraints are required to make sure that selected edges are really forming a route.
- ▶ A huge IP is constructed to save the company \$498 million in operational expenses over a 5-year period.
- ▶ Read the short story in Section 11.7 and the article on CEIBA.