# Algorithms 2023: Searching and Sorting

(Based on [Manber 1989])

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# 1 Binary Search

## Searching a Sorted Sequence

**Problem 1.** Let  $x_1, x_2, \dots, x_n$  be a sequence of real numbers such that  $x_1 \leq x_2 \leq \dots \leq x_n$ . Given a real number z, we want to find whether z appears in the sequence, and, if it does, to find an index i such that  $x_i = z$ .

Idea: cut the search space in half by asking only one question.

$$\begin{cases} T(1) = O(1) \\ T(n) = T(\frac{n}{2}) + O(1), n \ge 2 \end{cases}$$

Time complexity:  $O(\log n)$  (applying the master theorem with a = 1, b = 2, k = 0, and  $b^k = 1 = a$ ).

#### **Binary Search**

```
function Find (z, Left, Right) : integer;

begin

if Left = Right then

if X[Left] = z then Find := Left

else Find := 0

else

Middle := \lceil \frac{Left + Right}{2} \rceil;

if z < X[Middle] then

Find := Find(z, Left, Middle - 1)

else

Find := Find(z, Middle, Right)

end
```

Algorithm Binary\_Search (X, n, z); begin Position := Find(z, 1, n); end

**Binary Search: Alternative** 

```
 \begin{array}{ll} \textbf{function Find } (z, Left, Right) : integer; \\ \textbf{begin} \\ & \textbf{if } Left > Right \textbf{then} \\ & Find := 0 \\ & \textbf{else} \\ & Middle := \lceil \frac{Left + Right}{2} \rceil; \\ & \textbf{if } z = X[Middle] \textbf{then} \\ & Find := Middle \\ & \textbf{else if } z < X[Middle] \textbf{then} \\ & Find := Find(z, Left, Middle - 1) \\ & \textbf{else} \\ & Find := Find(z, Middle + 1, Right) \\ \end{array}
```

end

How do the two algorithms compare?

/\* The alternative may stop early once the target is found at Middle; otherwise, it spends another comparison to divide the search space. If by experience you expect to find the target almost all of the time, then consider using the alternative algorithm. \*/

## 1.1 Cyclically Sorted Sequence

### Searching a Cyclically Sorted Sequence

**Problem 2.** Given a cyclically sorted list, find the position of the minimal element in the list (we assume, for simplicity, that this position is unique).

• Example 1:

• Example 2:

• To cut the search space in half, what question should we ask?

/\* If X[Middle] < X[Right], then the minimal is in the left half (including X[Middle]); otherwise, it is in the right half (excluding X[Middle]). \*/

#### Cyclic Binary Search

Algorithm Cyclic\_Binary\_Search (X, n); begin  $Position := Cyclic_Find(1, n)$ ; end

function Cyclic\_Find (*Left*, *Right*) : *integer*; begin

if Left = Right then  $Cyclic_Find := Left$ 

else

```
Middle := \lfloor \frac{Left + Right}{2} \rfloor;

if X[Middle] < X[Right] then

Cyclic\_Find := Cyclic\_Find(Left, Middle)

else

Cyclic\_Find := Cyclic\_Find(Middle + 1, Right)
```

end

## 1.2 "Fixpoints"

## "Fixpoints"

**Problem 3.** Given a sorted sequence of distinct integers  $a_1, a_2, \dots, a_n$ , determine whether there exists an index i such that  $a_i = i$ .

• Example 1:

• Example 2:

• Again, can we cut the search space in half by asking only one question?

/\* As the numbers are distinct, they increase or decrease at least as fast as the indices (which always increase or decrease by one). If X[Middle] < Middle, then the fixpoint (if it exists) must be in the right half (excluding X[Middle]); otherwise, it must be in the left half (including X[Middle]). \*/

## A Special Binary Search

```
 \begin{array}{ll} \textbf{function Special_Find } (Left, Right) : integer; \\ \textbf{begin} \\ \textbf{if } Left = Right \textbf{then} \\ \textbf{if } A[Left] = Left \textbf{then } Special_Find := Left \\ \textbf{else } Special_Find := 0 \\ \textbf{else} \\ Middle := \lfloor \frac{Left+Right}{2} \rfloor; \\ \textbf{if } A[Middle] < Middle \textbf{then} \\ Special_Find := Special_Find(Middle + 1, Right) \\ \textbf{else} \\ Special_Find := Special_Find(Left, Middle) \\ \end{array}
```

 $\mathbf{end}$ 

A Special Binary Search (cont.)

```
Algorithm Special_Binary_Search (A, n);
begin
Position := Special_Find(1, n);
end
```

## 1.3 Stuttering Subsequence

### Stuttering Subsequence

**Problem 4.** Given two sequences  $A (= a_1 a_2 \cdots a_n)$  and  $B (= b_1 b_2 \cdots b_m)$ , find the maximal value of *i* such that  $B^i$  is a subsequence of A.

- If B = xyzzx, then  $B^2 = xxyyzzzxx$ ,  $B^3 = xxxyyyzzzzxxx$ , etc.
- B is a subsequence of A if we can embed B inside A in the same order but with possible holes.
- For example,  $B^2 = xxyyzzzxx$  is a subsequence of xxzzyyyyxxzzzzxxx.
- If  $B^j$  is a subsequence of A, then  $B^i$  is a subsequence of A, for  $1 \le i \le j$ .
- The maximum value of *i* cannot exceed  $\lfloor \frac{n}{m} \rfloor$  (or  $B^i$  would be longer than A).

#### Stuttering Subsequence (cont.)

Two ways to find the maximum i:

- Sequential search: try 1, 2, 3, etc. sequentially. Time complexity: O(nj), where j is the maximum value of i.
- Binary search between 1 and  $\lfloor \frac{n}{m} \rfloor$ .

Time complexity:  $O(n \log \frac{n}{m})$ .

Can binary search be applied, if the bound  $\lfloor \frac{n}{m} \rfloor$  is unknown?

Think of the base case in a reversed induction.

/\* Try 2<sup>0</sup>, 2<sup>1</sup>, 2<sup>2</sup>,  $\cdots$ , 2<sup>k-1</sup>, and 2<sup>k</sup> sequentially. If the target falls between 2<sup>k-1</sup> and 2<sup>k</sup>, apply binary search within that region. \*/

# 2 Interpolation Search

## Interpolation Search

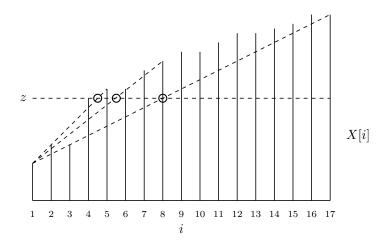
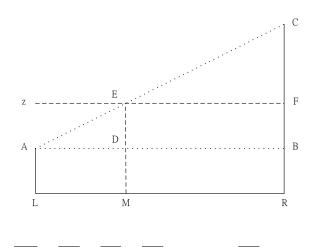


Figure: Interpolation search.

Source: redrawn from [Manber 1989, Figure 6.4].

## Interpolation Search (cont.)



$$\frac{LM}{\overline{LR}} = \frac{AD}{\overline{AB}} = \frac{AE}{\overline{AC}} = \frac{BF}{\overline{BC}}, \text{ so } |\overline{LM}| = \frac{|BF|}{|\overline{BC}|} \times |\overline{LR}|$$

## Interpolation Search (cont.)

 $\begin{array}{ll} \textbf{function Int\_Find} \ (z, \textit{Left}, \textit{Right}) : integer; \\ \textbf{begin} \\ \textbf{if} \ X[\textit{Left}] = z \ \textbf{then} \ \textit{Int\_Find} := \textit{Left} \\ \textbf{else} \ \textbf{if} \ \textit{Left} = \textit{Right} \ \text{or} \ X[\textit{Left}] = X[\textit{Right}] \ \textbf{then} \\ \textit{Int\_Find} := 0 \\ \textbf{else} \\ \\ \textit{Next\_Guess} := \lceil \textit{Left} + \frac{(z - X[\textit{Left}])(\textit{Right} - \textit{Left})}{X[\textit{Right}] - X[\textit{Left}]} \rceil; \\ \textbf{if} \ z < X[\textit{Next\_Guess}] \ \textbf{then} \\ \textit{Int\_Find} := \textit{Int\_Find}(z, \textit{Left}, \textit{Next\_Guess} - 1) \\ \textbf{else} \\ \\ \\ \textit{Int\_Find} := \textit{Int\_Find}(z, \textit{Next\_Guess}, \textit{Right}) \\ \end{array}$ 

end

/\* Next\_Guess - Left = 
$$|\overline{LM}| = \frac{|\overline{BF}|}{|\overline{BC}|} \times |\overline{LR}| \approx \left\lceil \frac{(z - X[Left])(Right - Left)}{X[Right] - X[Left]} \right\rceil */$$

Interpolation Search (cont.)

Algorithm Interpolation\_Search (X, n, z); begin

if z < X[1] or z > X[n] then Position := 0else  $Position := Int\_Find(z, 1, n);$ 

## end

# 3 Sorting

Sorting

**Problem 5.** Given n numbers  $x_1, x_2, \dots, x_n$ , arrange them in increasing order. In other words, find a sequence of distinct indices  $1 \leq i_1, i_2, \cdots, i_n \leq n$ , such that  $x_{i_1} \leq x_{i_2} \leq \cdots \leq x_{i_n}$ .

A sorting algorithm is called **in-place** if no additional work space is used besides the initial array that holds the elements.

#### 3.1Using Balanced Search Trees

#### Using Balanced Search Trees

- Balanced search trees, such as AVL trees, may be used for sorting:
  - 1. Create an empty tree.
  - 2. Insert the numbers one by one to the tree.
  - 3. Traverse the tree and output the numbers.
- What's the time complexity? Suppose we use an AVL tree.

/\* The time complexity is  $O(n \log n)$ , as there are n elements to insert and each insertion takes  $O(\log n)$ time. Traversal of the tree can be done efficiently in O(n) time. \*/

#### 3.2 **Radix Sort**

## **Radix Sort**

```
Algorithm Straight_Radix (X, n, k);
begin
    put all elements of X in a queue GQ;
    for i := 1 to d do
        initialize queue Q[i] to be empty
    for i := k downto 1 do
        while GQ is not empty do
              pop x from GQ;
              d := the i-th digit of x;
              insert x into Q[d];
        for t := 1 to d do
            insert Q[t] into GQ;
    for i := 1 to n do
        pop X[i] from GQ
```

end

Time complexity: O(nk).

#### 3.3Merge Sort

## Merge Sort

```
Algorithm Mergesort (X, n);
begin M\_Sort(1,n) end
procedure M_Sort (Left, Right);
begin
   if Right - Left = 1 then
```

 $\begin{array}{l} \mbox{if } X[Left] > X[Right] \mbox{ then } swap(X[Left], X[Right]) \\ \mbox{else if } Left \neq Right \mbox{ then } \\ Middle := \lceil \frac{1}{2}(Left + Right) \rceil; \\ M\_Sort(Left, Middle - 1); \\ M\_Sort(Middle, Right); \end{array}$ 

## Merge Sort (cont.)

$$\begin{split} i &:= Left; \ j := Middle; \ k := 0; \\ \textbf{while} \ (i \leq Middle - 1) \ \text{and} \ (j \leq Right) \ \textbf{do} \\ k &:= k + 1; \\ & \textbf{if} \ X[i] \leq X[j] \ \textbf{then} \\ TEMP[k] &:= X[i]; \ i := i + 1 \\ & \textbf{else} \ TEMP[k] := X[j]; \ j := j + 1; \\ \textbf{if} \ j > Right \ \textbf{then} \\ & \textbf{for} \ t := 0 \ \textbf{to} \ Middle - 1 - i \ \textbf{do} \\ X[Right - t] &:= X[Middle - 1 - t] \\ \textbf{for} \ t := 0 \ \textbf{to} \ k - 1 \ \textbf{do} \\ X[Left + t] &:= TEMP[1 + t] \end{split}$$

end

/\* In the merging stage, the while loop terminates when one of the two halves is exhausted. If the left half is exhausted ( $j \leq Right$ ), the remaining elements in the right half are already in the correct positions in Array X and so nothing needs to be done. \*/

Time complexity:  $O(n \log n)$ .

/\*

$$\left\{ \begin{array}{l} T(1)=O(1)\\ T(n)=2T(\frac{n}{2})+O(n), n\geq 2 \end{array} \right.$$

Apply the master theorem with a = 2, b = 2, k = 1, and  $b^k = 2 = a$ ). \*/

## Merge Sort (cont.)

6	2	8	5	10	9	12	1	15	7	3	13	4	11	16	14
2	6	8	5	10	9	12	1	15	7	3	13	4	11	16	14
2	6	5	8	10	9	12	1	15	7	3	13	4	11	16	14
2	5	6	8	10	9	12	1	15	7	3	13	4	11	16	14
2	5	6	8	9	(10)	12	1	15	7	3	13	4	11	16	14
2	5	6	8	9	10	1	(12)	15	7	3	13	4	11	16	14
2	5	6	8	1	9	(10)	(12)	15	7	3	13	4	11	16	14
1	2	5	6	8	9	(10)	(12)	15	7	3	13	4	11	16	14
1	2	5	6	8	9	10	12	7	(15)	3	13	4	11	16	14
1	2	5	6	8	9	10	12	7	15	3	(13)	4	11	16	14
1	2	5	6	8	9	10	12	3	7	(13)	(15)	4	11	16	14
1	2	5	6	8	9	10	12	3	7	13	15	4	(11)	16	14
1	2	5	6	8	9	10	12	3	7	13	15	4	11	(14)	(16)
1	2	5	6	8	9	10	12	3	7	13	15	4	(11)	(14)	(16)
1	2	5	6	8	9	10	12	3	4	$\overline{\mathcal{O}}$	(11)	(13)	(14)	(15)	(16)
1	2	3	4	5	6	$\bigcirc$	8	9	10	(11)	(12)	(13)	(14)	(15)	(16)

Figure: An example of mergesort.

Source: redrawn from [Manber 1989, Figure 6.8].

/\* The table shows the order in which all the merges occur. However, it does not show the movements of the elements from the array to the temporary array and back. \*/

## 3.4 Quick Sort

Quick Sort

Algorithm Quicksort (X, n); begin  $Q\_Sort(1, n)$ end

```
procedure Q_Sort (Left, Right);
begin
if Left < Right then
Partition(X, Left, Right);
Q_Sort(Left, Middle - 1);
Q_Sort(Middle + 1, Right)
```

 $\mathbf{end}$ 

Time complexity:  $O(n^2)$ , but  $O(n \log n)$  in average

/\* The worst-case time complexity  $O(n^2)$  occurs when the input array is already sorted or nearly sorted, as each partition (which is of time O(n)) will successively divide the array into two parts of sizes 1 and n-2, 1 and n-4, 1 and n-6, etc. This may be avoided by choosing the pivot more "wisely". \*/

## Quick Sort (cont.)

```
\begin{array}{l} \textbf{Algorithm Partition}(X, Left, Right);\\ \textbf{begin}\\ pivot := X[Left];\\ L := Left; \ R := Right;\\ \textbf{while} \ L < R \ \textbf{do}\\ \textbf{while} \ X[L] \leq pivot \ \text{and} \ L \leq Right \ \textbf{do} \ L := L + 1;\\ \textbf{while} \ X[R] > pivot \ \text{and} \ R \geq Left \ \textbf{do} \ R := R - 1;\\ \textbf{if} \ L < R \ \textbf{then} \ swap(X[L], X[R]);\\ Middle := R;\\ swap(X[Left], X[Middle])\\ \textbf{end} \end{array}
```

## Quick Sort (cont.)

6	2	8	5	10	9	12	1	15	7	3	13	4	11	16	14
6	2	4	5	10	9	12	1	15	7	3	13	8	11	16	14
6	2	4	5	3	9	12	1	15	7	10	13	8	11	16	14
6	2	4	5	3	1	12	9	15	7	10	13	8	11	16	14
1	2	4	5	3	6	12	9	15	7	10	13	8	11	16	14

Figure: Partition of an array around the pivot 6. Source: redrawn from [Manber 1989, Figure 6.10].

## Quick Sort (cont.)

6	2	8	5	10	9	12	1	15	7	3	13	4	11	16	14
1	2	4	5	3	6	12	9	15	7	10	13	8	11	16	14
1	2	4	5	3	6	12	9	15	7	10	13	8	11	16	14
1	2	4	5	3	6	12	9	15	7	10	13	8	11	16	14
1	2	3	4	5	6	12	9	15	7	10	13	8	11	16	14
1	2	3	4	5	6	8	9	11	7	10	(12)	13	15	16	14
1	2	3	4	5	6	7	8	11	9	10	(12)	13	15	16	14
1	2	3	4	5	6	7	8	10	9	(11)	(12)	13	15	16	14
1	2	3	4	5	6	7	8	9	10	(11)	(12)	13	15	16	14
1	2	3	4	5	6	7	8	9	(10)	(11)	(12)	(13)	15	16	14
1	2	3	4	5	6	7	8	9	(10)	(11)	(12)	(13)	14	(15)	16

Figure: An example of quicksort. Source: redrawn from [Manber 1989, Figure 6.12].

### Average-Case Complexity of Quick Sort

• When X[i] is selected (at random) as the pivot,

$$T(n) = n - 1 + T(i - 1) + T(n - i)$$
, where  $n \ge 2$ .

The average running time will then be

$$T(n) = n - 1 + \frac{1}{n} \sum_{i=1}^{n} (T(i-1) + T(n-i))$$
  
=  $n - 1 + \frac{1}{n} \sum_{i=1}^{n} T(i-1) + \frac{1}{n} \sum_{i=1}^{n} T(n-i)$   
=  $n - 1 + \frac{1}{n} \sum_{j=0}^{n-1} T(j) + \frac{1}{n} \sum_{j=0}^{n-1} T(j)$   
=  $n - 1 + \frac{2}{n} \sum_{i=0}^{n-1} T(i)$ 

• Solving this recurrence relation with full history,  $T(n) = O(n \log n)$ .

## 3.5 Heap Sort

## Heap Sort

```
Algorithm Heapsort (A, n);
begin
Build_Heap(A);
for i := n downto 2 do
swap(A[1], A[i]);
Rearrange_Heap(i - 1)
```

## end

Time complexity:  $O(n \log n)$ 

/\* The complexity is so, mainly thanks to the efficiency of Rearrange\_Heap, which is  $O(\log n)$ . \*/

Heap Sort (cont.) procedure Rearrange\_Heap (k); begin parent := 1; child := 2; while  $child \le k - 1$  do if A[child] < A[child + 1] then child := child + 1; if A[child] > A[parent] then swap(A[parent], A[child]); parent := child; child := 2 \* childelse child := k

end

Heap Sort (cont.)

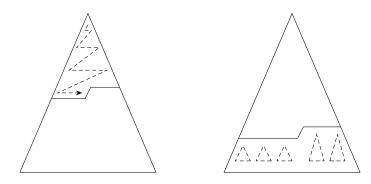


Figure: Top down and bottom up heap construction. Source: redrawn from [Manber 1989, Figure 6.14].

How do the two approaches compare?

/\* Top down:  $O(n \log n)$ .

Bottom up: O(sum of the heights of all nodes) = O(n). Consider a full binary tree of height h. From an excercise problem in HW#2, we know that "sum of the heights of all nodes" of the tree equals  $2^{h+1} - (h+2) \le 2^{h+1} - 1 = n$ . \*/

#### Building a Heap Bottom Up

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
6	2	8	5	10	9	12	1	15	7	3	13	4	11	16	14
6	2	8	5	10	9	12	(14)	15	7	3	13	4	11	16	1
6	2	8	5	10	9	(16)	14	15	7	3	13	4	11	(12)	1
6	2	8	5	10	(13)	16	14	15	7	3	9	4	11	12	1
6	2	8	5	10	13	16	14	15	7	3	9	4	11	12	1
6	2	8	(15)	10	13	16	14	5	7	3	9	4	11	12	1
6	2	(16)	15	10	13	(12)	14	5	7	3	9	4	11	8	1
6	(15)	16	(14)	10	13	12	2	5	7	3	9	4	11	8	1
(16)	15	(13)	14	10	9	12	2	5	7	3	6	4	11	8	1

Figure: An example of building a heap bottom up. Source: adapted from [Manber 1989, Figure 6.15].

#### A Lower Bound for Sorting

- A lower bound for a particular problem is a proof that *no algorithm* can solve the problem better.
- We typically define a computation model and consider only those algorithms that fit in the model.
- **Decision trees** model computations performed by *comparison-based* algorithms.

**Theorem 6** (Theorem 6.1). Every decision-tree algorithm for sorting has height  $\Omega(n \log n)$ .

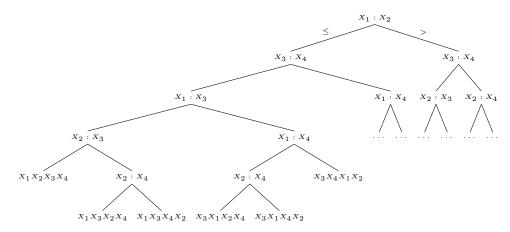
Proof idea: there must be at least n! leaves in the decision tree, one for each possible outcome.

/\* Recall Stirling's approximation:  $n! = \sqrt{2\pi n} \left(\frac{n}{e}\right)^n (1 + O(1/n))$ . The height of the decision tree must be at least log(n!), i.e.,  $\Omega(n \log n)$ . \*/

Is the lower bound contradictory to the time complexity of radix sort?

#### A Lower Bound for Sorting (cont.)

A decision tree (partly shown) for the merge sort with  $X_1X_2X_3X_4$  as input:



Note: in total, there should be 4! = 24 leaves, only six of which are shown.

# 4 Order Statistics

#### Order Statistics: Minimum and Maximum

Problem 7. Find the maximum and minimum elements in a given sequence.

- The obvious solution requires (n-1) + (n-2) (= 2n-3) comparisons between elements.
- Can we do better? (Which comparisons could have been avoided?)

/\* A better algorithm: compare  $x_1$  and  $x_2$ . Set *min* to be the smaller of the two and *max* the larger. Compare  $x_3$  and  $x_4$  and then compare the smaller with *min* and the larger with *max*; these take three comparisons. Update *min* and *max* accordingly. Continue until we have exhausted the sequence of numbers. Assuming *n* is even, the total number of comparisons  $= 1 + 3 \times \frac{(n-2)}{2} = \frac{3}{2}n - 2$ . Suppose  $x_1 < x_2 < x_3 < x_4$ . Using the obvious solution to find the minimum and then the maximum, we would make the following six comparisons:  $x_1 : x_2, x_1 : x_3$ , and  $x_1 : x_4$  and then  $x_2 : x_3$  and  $x_3 : x_4$ . With the above algorithm, we will make just five comparisons:  $x_1 : x_2$ , and then  $x_3 : x_4, x_1 : x_3$ , and  $x_2: x_4$ . In particular, the comparison  $x_1: x_4$  (whose result may be inferred from  $x_1: x_3$  and  $x_3: x_4$ ) in the obvious solution has been avoided. \*/

#### **Order Statistics:** *Kth-Smallest*

**Problem 8.** Given a sequence  $S = x_1, x_2, \dots, x_n$  of elements, and an integer k such that  $1 \le k \le n$ , find the kth-smallest element in S.

### Order Statistics: Kth-Smallest (cont.)

```
procedure Select (Left, Right, k);
begin
    if Left = Right then
       Select := Left
    else Partition(X, Left, Right);
         let Middle be the output of Partition;
         if Middle - Left + 1 \ge k then
            Select(Left, Middle, k)
         else
            Select(Middle + 1, Right, k - (Middle - Left + 1))
end
```

Algorithm Selection (X, n, k); begin if (k < 1) or (k > n) then print "error" else S := Select(1, n, k)end

/\* Here the formal parameter k (for rank) is made to be relative to the left bound of array indices, while Left, Middle, and Right are absolute index values. \*/

#### **Order Statistics:** *Kth-Smallest* (cont.)

The nested "if" statement may be simplified:

```
procedure Select (Left, Right, k);
begin
    if Left = Right then
       Select := Left
    else Partition(X, Left, Right);
         let Middle be the output of Partition;
         if Middle > k then
            Select(Left, Middle, k)
         else
            Select(Middle + 1, Right, k)
```

end

# 5 Finding a Majority

### Finding a Majority

**Problem 9.** Given a sequence of numbers, find the majority in the sequence or determine that none exists.

A number is a *majority* in a sequence if it occurs more than  $\frac{n}{2}$  times in the sequence.

Caution: maintaining a counter for each possible number requires  $O(\log n)$  time for each access to a particular counter, which means  $O(n \log n)$  time in total. Sorting the sequence to find a probable candidate also requires  $O(n \log n)$  time.

Idea: compare any two numbers in the sequence. What can we conclude if they are not equal?

/\* If there is a majority, it is also a majority of the other n-2 numbers. However, the reverse may not be true. \*/

What if they are equal?

/\* Keep the first number as a candidate at hand and repeat the following:

If the next number equals the candidate, we increment the count of its occurrences; otherwise, we have a pair of unequal numbers to eliminate (by decrementing the count for the candidate). When the count becomes 0 (due to elimination), we take the next number as a new candidate. \*/

#### Finding a Majority (cont.)

```
Algorithm Majority (X, n);
begin
C := X[1]; M := 1;
for i := 2 to n do
if M = 0 then
C := X[i]; M := 1
else
if C = X[i] then M := M + 1
else M := M - 1;
```

Finding a Majority (cont.)

if M = 0 then Majority := -1else Count := 0;for i := 1 to n do if X[i] = C then Count := Count + 1;if Count > n/2 then Majority := Celse Majority := -1

end

Time complexity: O(n).